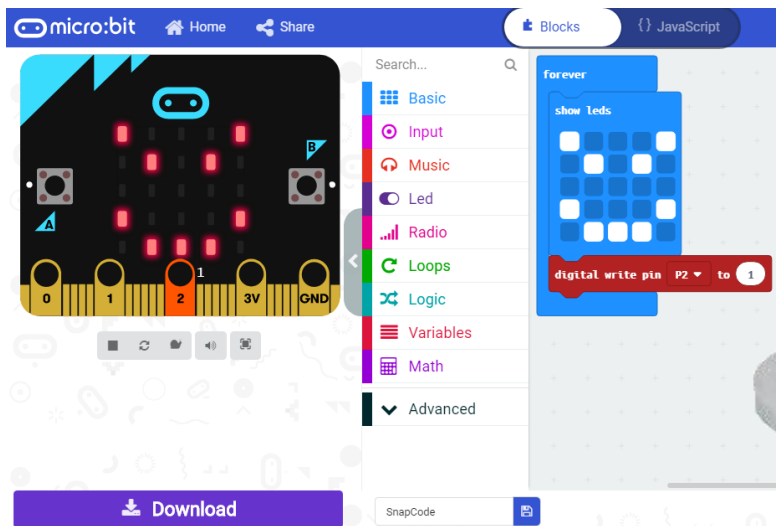


KODEKLIX®

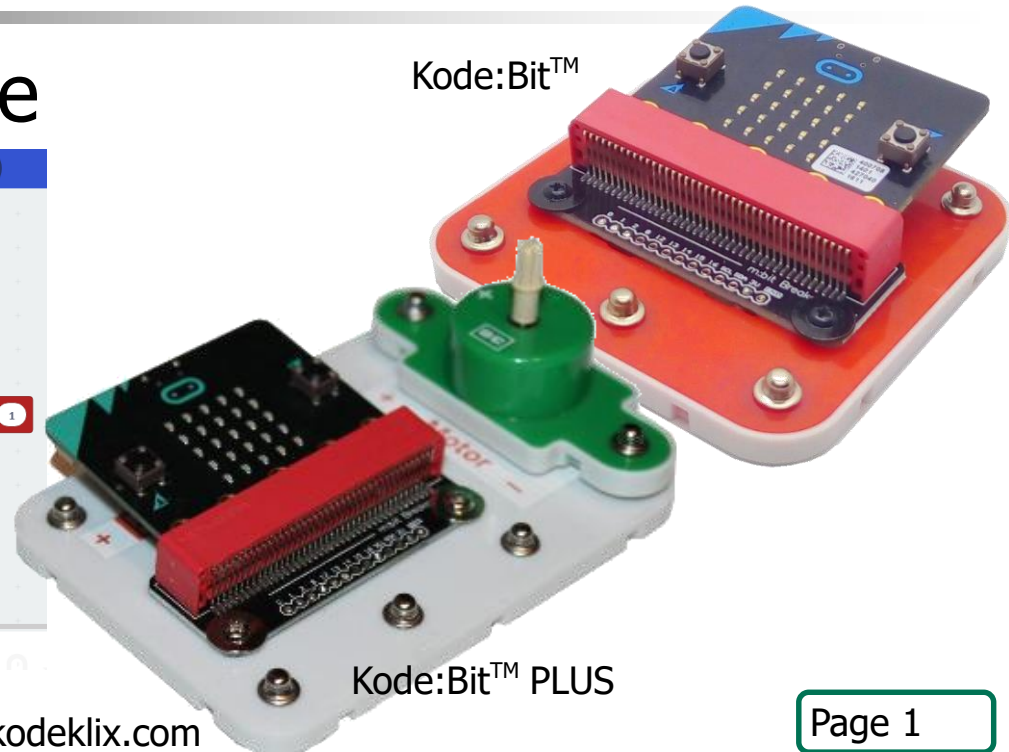


Kode:Bit for the BBC micro:bit

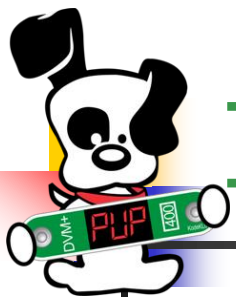
Quick Start Guide



Kode:Bit™



Kode:Bit™ PLUS



Introduction

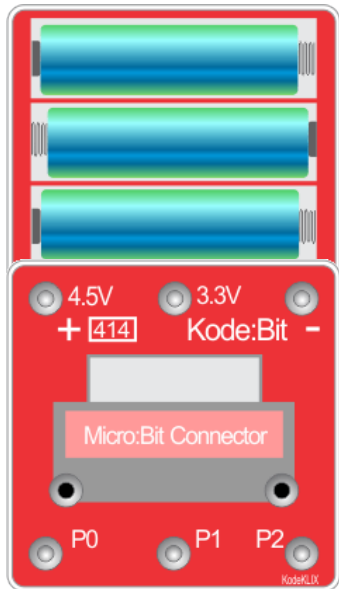
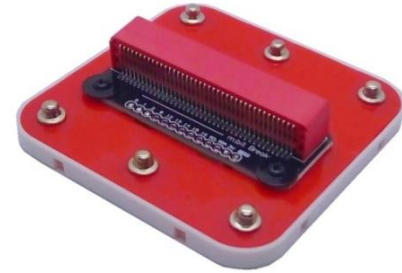
- Kode:Bit™ allows you to connector your BBC micro:bit board to:
 - Other snap controllers such as the SnapCPU™ for use as a co-process for display or other functionality
 - Build interfacing circuits using your KodeKLIX® or other compatible snap electronic components





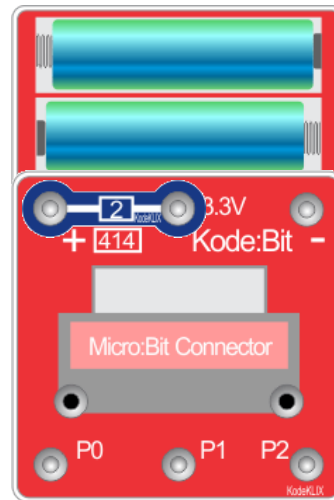
Power Configuration

- Your BBC micro:bit simply inserts into the connector on the Kode:Bit, but before doing so, consider how you will be using your micro:bit...



4.5V Battery Pack

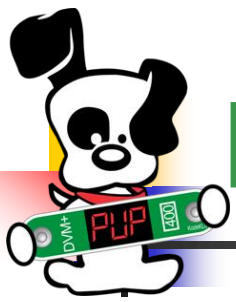
In this configuration **no link** is required. Internally, the voltage from battery pack [70] is reduced to the safe level needed for the micro:bit



3.0V Battery Pack

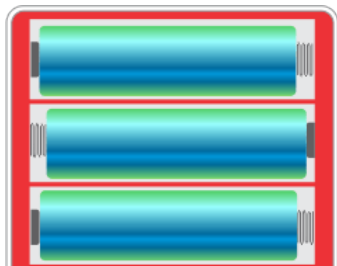
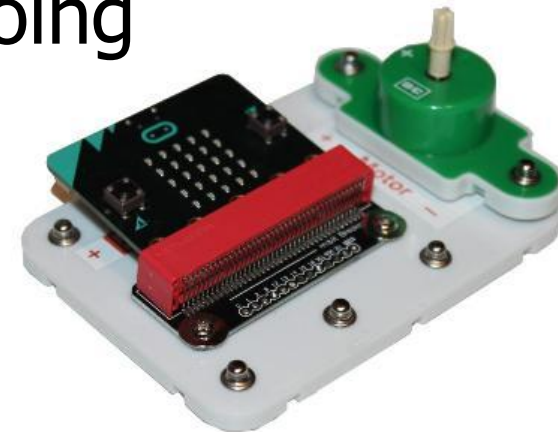
In this configuration a link may be required if your display is very dim or some of the micro:bit's sensors do not work reliably.

This configuration is also used if you power your Bit with the USB cable.

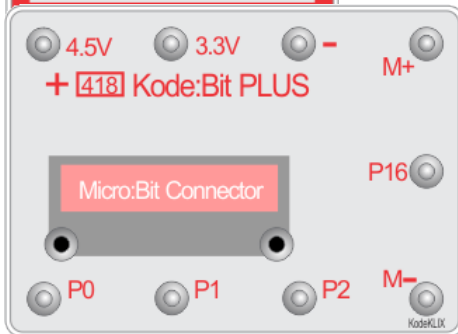


Power Configuration - PLUS

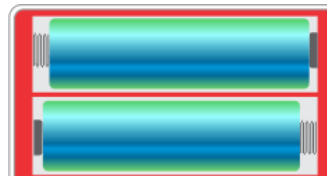
- Your BBC micro:bit simply inserts into the connector on the Kode:Bit PLUS, but before doing so, consider how you will be using your micro:bit...



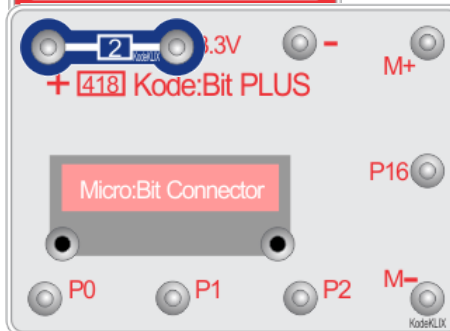
4.5V Battery Pack



In this configuration **no link** is required. Internally, the voltage from battery pack [70] is reduced to the safe level needed for the micro:bit

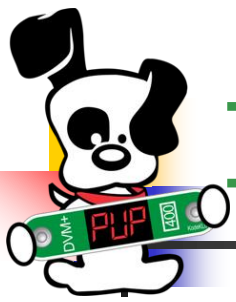


3.0V Battery Pack



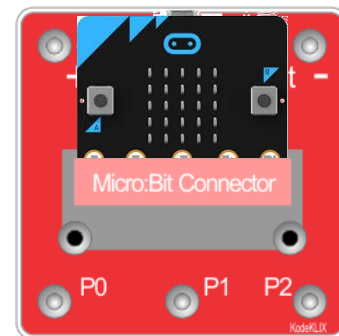
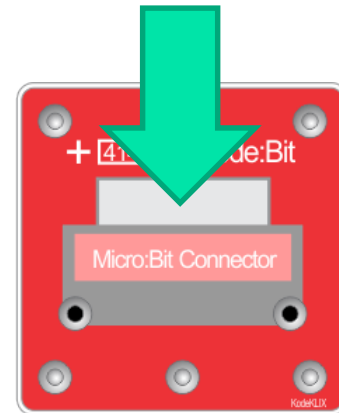
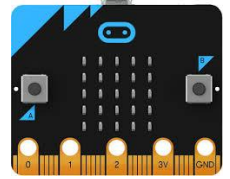
In this configuration a link may be required if your display is very dim or some of the micro:bit's sensors do not work reliably.

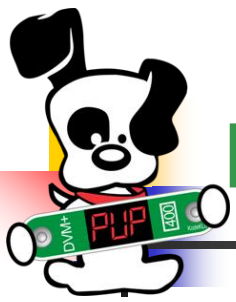
This configuration is also used if you power your Bit with the USB cable.



Inserting the micro:bit

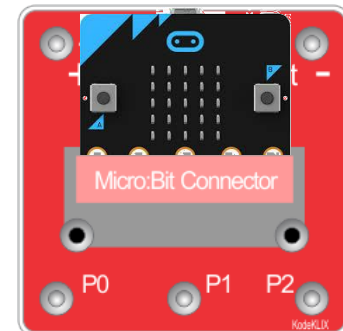
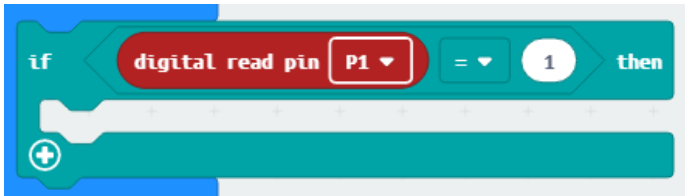
- Once you have decided on whether to use the power link or not, the micro:bit can be easily inserted into the Kode:Bit adaptor
- Power and ground (0V) are supplied to the micro:bit through the top snaps
- Input/Output pins P0, P1 and P2 are routed as shown
 - These pins are yours to use, but remember all the connection rules for the micro:bit still apply

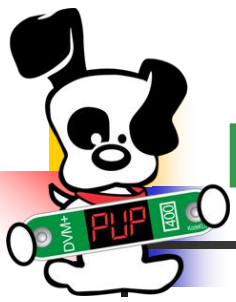




micro:bit Coding

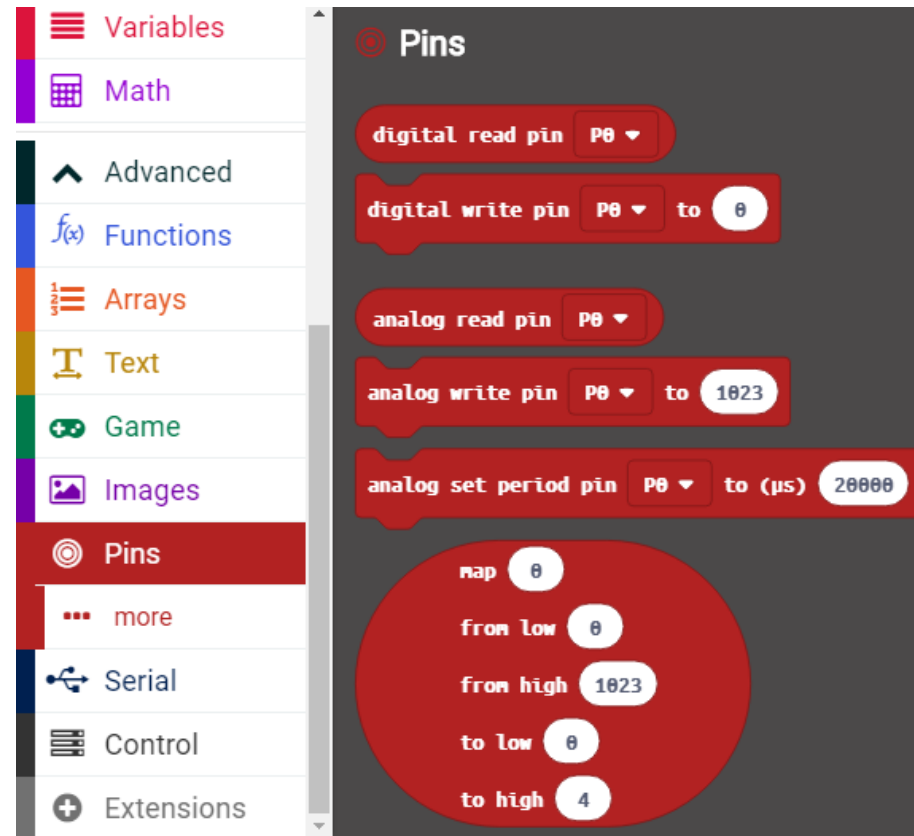
- Making code for the micro:bit is the same as usual, using the on-line MakeCode utilities at <http://makecode.microbit.org/#editor>
- Downloading code for the micro:bit is the same as usual, using the USB cable and drag-and-drop method
- Basic pin I/O can be controlled with these MakeCode Blocks





micro:bit I/O Coding Blocks

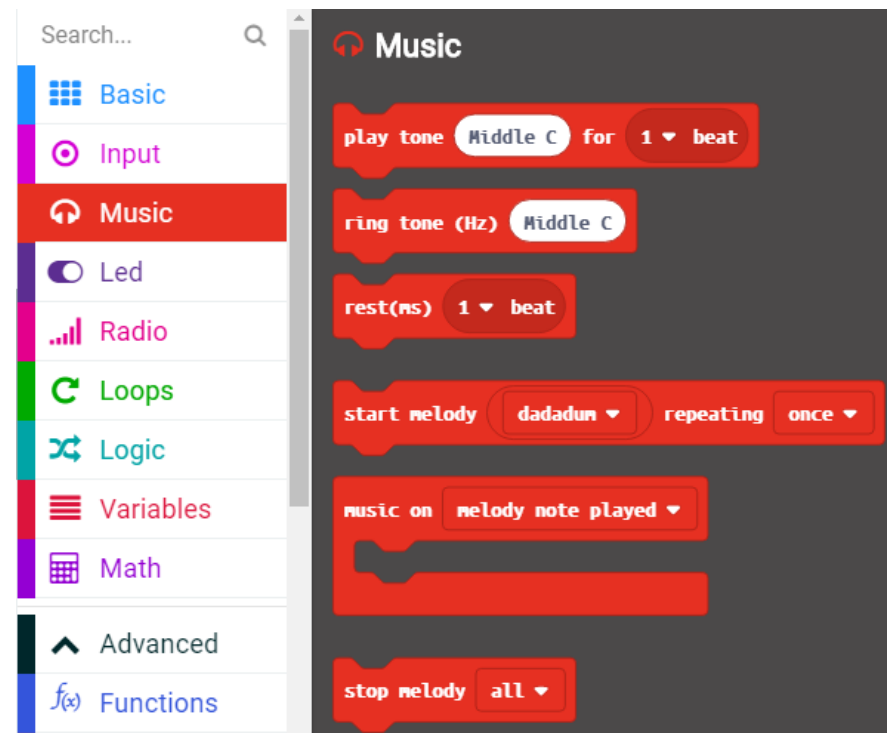
- Various coding blocks can be found under the Pins menu in the advanced section
- Digital I/O is where signals are either ON (1) or OFF (0)
- Analog inputs are signals which have a value between 0-255





micro:bit Music Coding

- By default, the micro:bit plays all sounds and music through P0
- Since the micro:bit has no built-in speaker so an external speaker [20] or piezo [11] will need to be connected





Example Project 1.0

Push button input to the Kode:Bit™

- Assemble the snap components as shown in circuit 1.0; Construct the MakeCode below and download to the micro:bit
- The battery pack [70] is for powering the circuit (and the micro:bit when not on USB)

```

forever
  if digital read pin P1 == 1 then
    show leds
    digital write pin P2 to 1
    start melody d4a4a4a4 repeating once
  else
    stop melody all
    show leds
    digital write pin P2 to 0
  
```

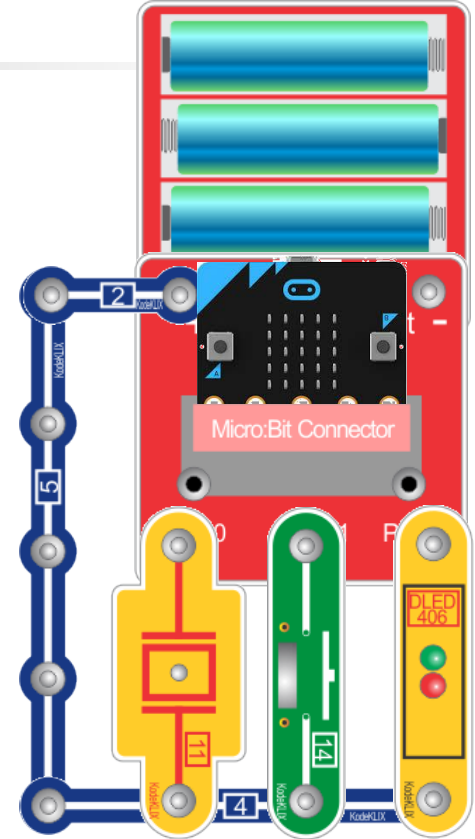
**code set to read from inputP1

**illuminates the DLED on P2

**plays tune through piezo on P0

Connecting to "high" is the equivalent of connecting to the +ve terminal of the battery box.

A push-button switch is momentary (only valid when being pressed) so needs to be held until the code "sees" it.



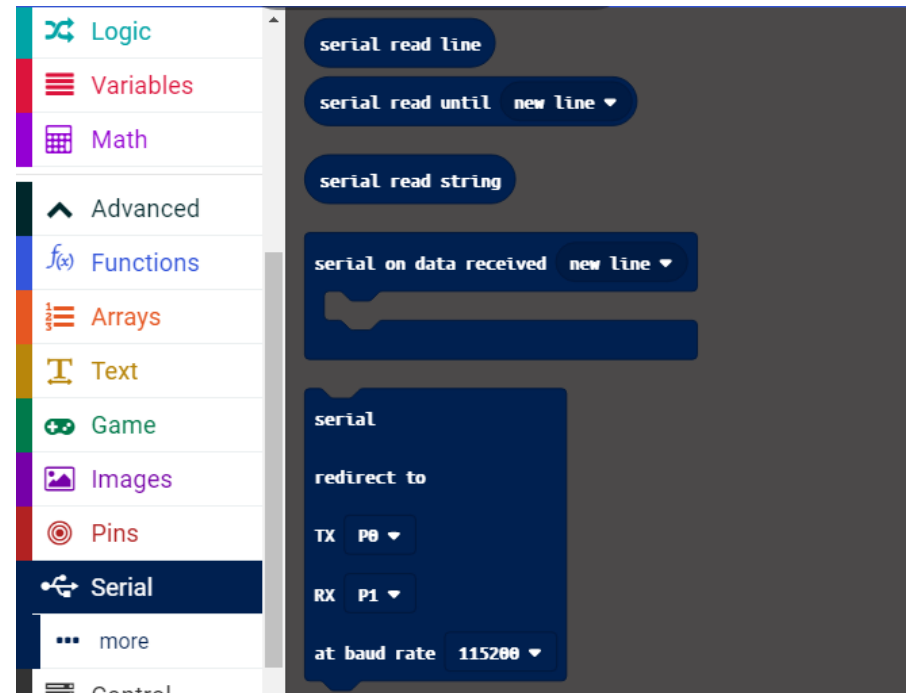
Circuit 1.0

Challenge: modify the code to make P2 stay lit for a fixed time after the button P1 is pressed.



Advanced micro:bit I/O Coding

- Various coding blocks can be found under the Pins menu in the advanced section
- Digital I/O is where signals are either ON (1) or OFF (0)
- Analog inputs are signals which have a value between 0-255

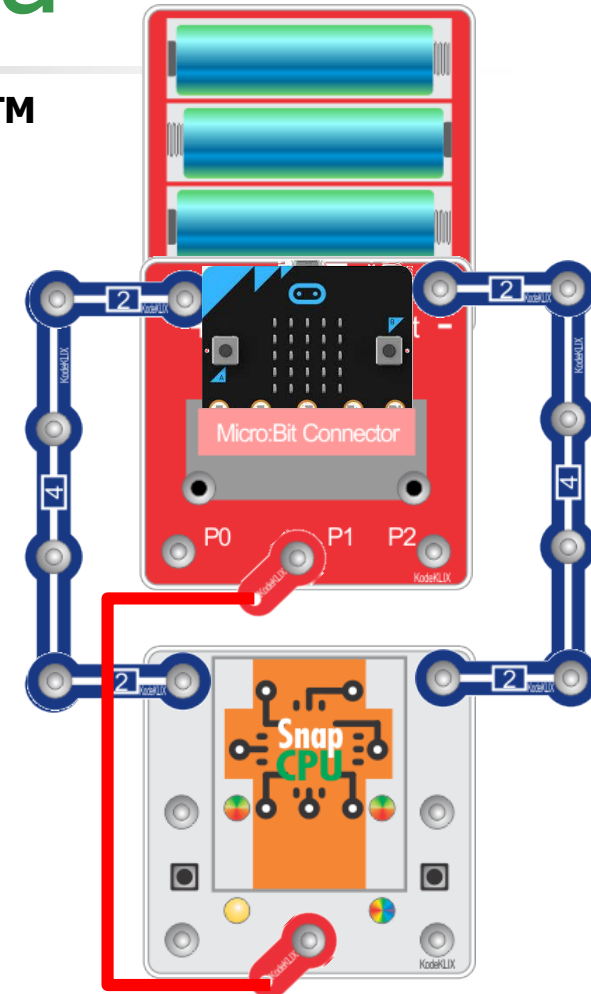




Example Project 2.0a

Using the micro:bit with the SnapCPU™

- This project demonstrates how to computers, the SnapCPU and the micro:bit can be made to communicate
- In this project, the micro:bit is a display for the SnapCPU™
- Assemble the snap components as shown in circuit 2.0
- Construct the MakeCode on the next page and download to the micro:bit
- Construct the Blockly code on the next page and download it to the SnapCPU™
- If all goes to plan, the micro:bit display show A, B, C, ...



Circuit 2.0



Example Project 2.0b

Using the micro:bit with the SnapCPU™

```

start
  wait for 5 Second(s)
  serial output at T4800 on C.2 13
  send as ASCII
  forever
  do
    count with varA from 65 to 90 by 1
    do
      serial output at T4800 on C.2 varA
      send as ASCII
      serial output at T4800 on C.2 13
      send as ASCII
    pause for 500 ms
  
```

The BBC micro:bit is very slow to wake up, so allow 5seconds. It is only capable of True Signal Level RS232, and needs a CR (code 13) to reliably acknowledge data is available in its RS232 input buffer.

**send data as the ASCII codes; after each letter send a CR code so the micro:bit knows to read the data that was sent

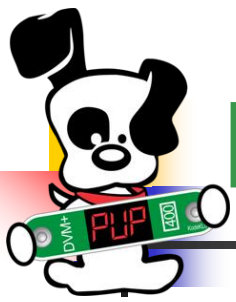
Challenge: modify the code in the SnapCPU to send a message letter by letter, rather than the ABCDE sequence of characters... you can do it by codes or characters!

```

micro:bit Home Share Blocks
on start
  serial
  redirect to
  TX P0
  RX P1
  at baud rate 4800
  forever
  show string serial read string
  
```

**receive and display the information which was sent

**setup for serial protocols to be used; these must match on both the micro:bit and SnapCPU



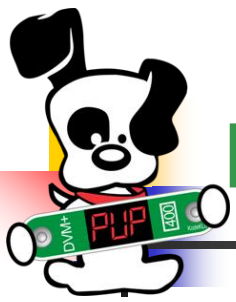
Kode:Bit™ Motor Driver Blocks

- To simplify the control of motors, install this driver as an extension to MakeCode:

<http://github.com/waveshare/pxt-Motor>

1. Open extensions menu
2. Enter the web link details
3. A new block menu is added!

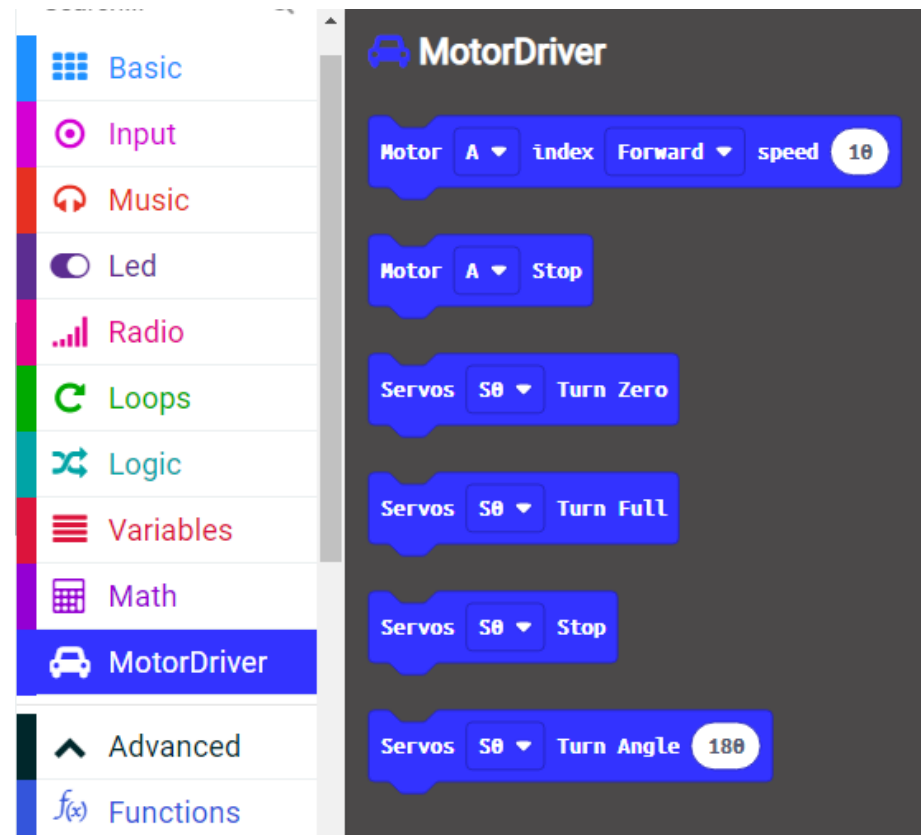
The image contains three screenshots from the MakeCode editor. The first screenshot shows the 'Extensions' menu in the left sidebar, with the 'Extensions' option circled in red. The second screenshot shows the 'Extensions' page with the URL 'http://github.com/waveshare/pxt-Motor' entered in the search bar and circled in red. The third screenshot shows the 'MotorDriver' extension installed, with the 'MotorDriver' option in the left sidebar circled in red. The main workspace shows a block diagram with motor control blocks like 'Motor A Forward' and 'Motor A Stop'.

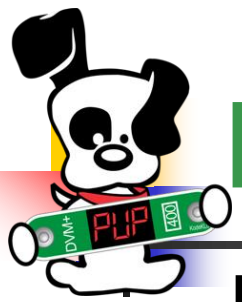


micro:bit Motor Coding Blocks

- Various coding blocks can be found under the new MotorDriver menu
- Motor 'A' is used
- The first block controls motor direction and speed
- The second block stops the motor

Note: driver may need to be installed for each new project





Example Project 3.0

Motor control with the Kode:Bit™ PLUS

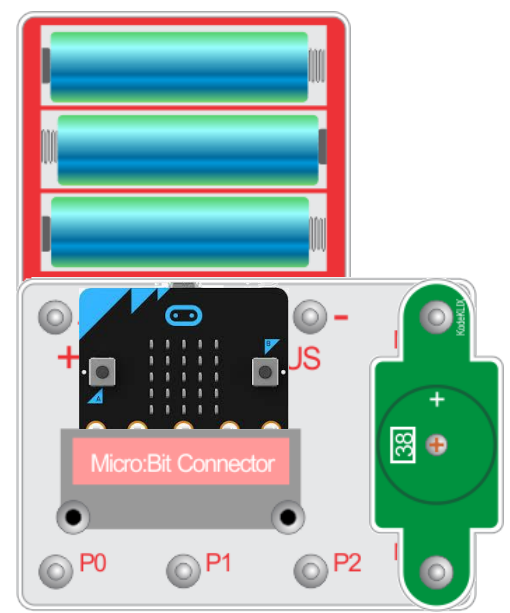
- This project demonstrates how to control a motor from the micro:bit
- Assemble the snap components as shown in circuit 3.0
- Construct and download the MakeCode shown below
- If all goes to plan, the micro:bit display show the direction F, S, R as the motor spins forward, stops and then backwards

Note: driver may need to be installed for each new project

```

forever
  show string "F"
  Motor A index Forward speed 10
  pause (ms) 2000
  show string "S"
  Motor A Stop
  pause (ms) 2000
  show string "R"
  Motor A index Backward speed 4
  pause (ms) 2000

```



Circuit 3.0



What Next...?

- The internet is has many example projects for the micro:bit
 - Try building these using snap parts rather than tiny components and clips
 - Think of other creative ways to use the power of two CPUs connected at the same time
 - Send / receive data
 - Send / receive signals